**LAB 02**

**COMPUTER ORGANIZATION**

**AND ASSEMBLY LANG(COAL)**

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**NATIONAL UNIVERSITY OF COMPUTER AND EMERGING SCIENCES**

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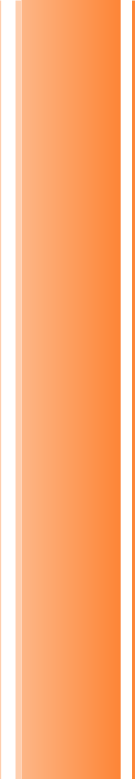
Prepared by:

Amin Sadiq

Version:

Date:

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Lab Session 02

**Objectives:**

* Debugging of programs
* Basic elements of Assembly language
* Defining Data
* Intrinsic Data Types

**Steps Involved in Creating and Running a Program:**

**ASSEMBLE R:**

It converts the assembly language to machine language (Object Code) May contain unresolved references (i.e. file contains some or all of complete program)



**LINKER:**

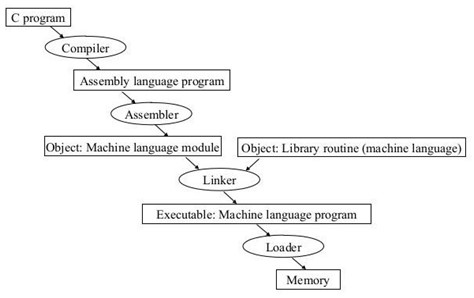
A program that combines object files to create a single “executable” file. Major functional difference is that all references are resolved. (i.e. Program contains all parts needed to run) A program that loads executable files into memory, and may initialize some registers (e.g. IP) and starts it going.

**DEBUGGER:**

A program that loads but controls the execution of the program. To start/stop execution, to view and modify state variables.

**STEPS IN CREATING & RUNNING CODE:**





# SECTION 1: DEBUGGING OUR PROGRAM

We have seen how to configure Visual Studio 2019 for Assembly Language and tested it with a sample program. The output of our sample program was displayed using a console window but it is usually more desirable to watch the step by step execution of our program with each line of code using breakpoints.

Let us briefly define the keywords relevant to debugging in Visual Studio and then we will cover an example for understanding.

## DEBUGGER

The (Visual Studio) debugger helps us observe the run-time behavior of our program and find problems. With the debugger, we can break the execution of our program to examine our code, examine and edit variables, view registers, see the instructions created from our source code, and view the memory space used by our application.

## BREAKPOINT

A breakpoint is a signal that tells the debugger to temporarily suspend execution of your program at a certain point. When execution is suspended at a breakpoint, your program is said to be in break mode.

## CODE STEPPING

One of the most common debugging procedures is stepping: executing code one line at a time. The Debug menu provides three commands for stepping through code:

* Step Into (By pressing F11)
* Step Over (By pressing F10)
* Step Out (Shift+F11)



## SINGLE STEPPING

To see the values of internal registers and memory variables during execution, let us use an example.

Copy the following code onto your Test.asm file.k

TITLE Add and Subtract

INCLUDE Irvine32.inc

.code

main PROC

mov eax, 10000h ; EAX =10000h add eax, 40000h ; EAX =50000h

sub eax, 20000h ; EAX =30000h

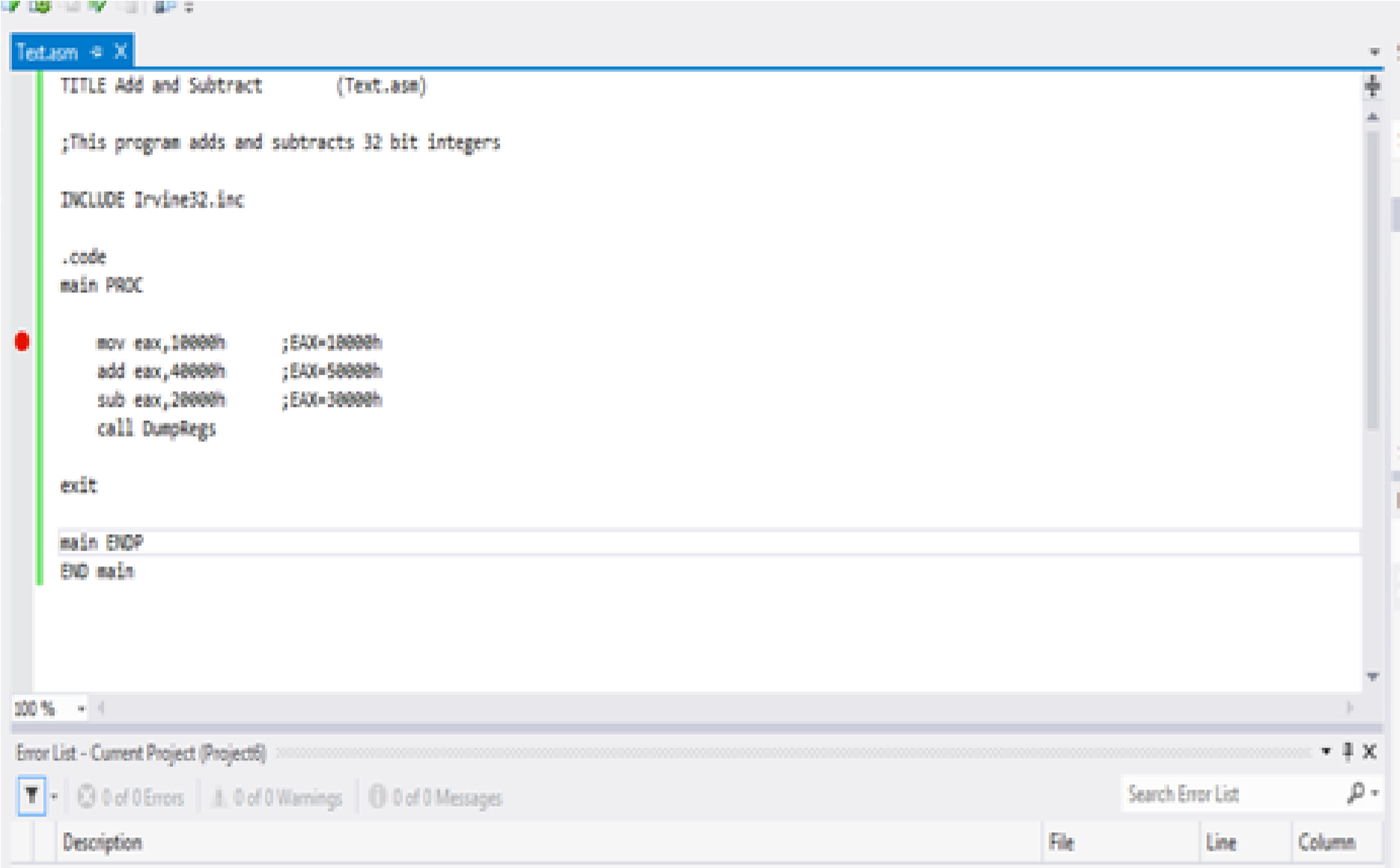
call DumpRegs

exit

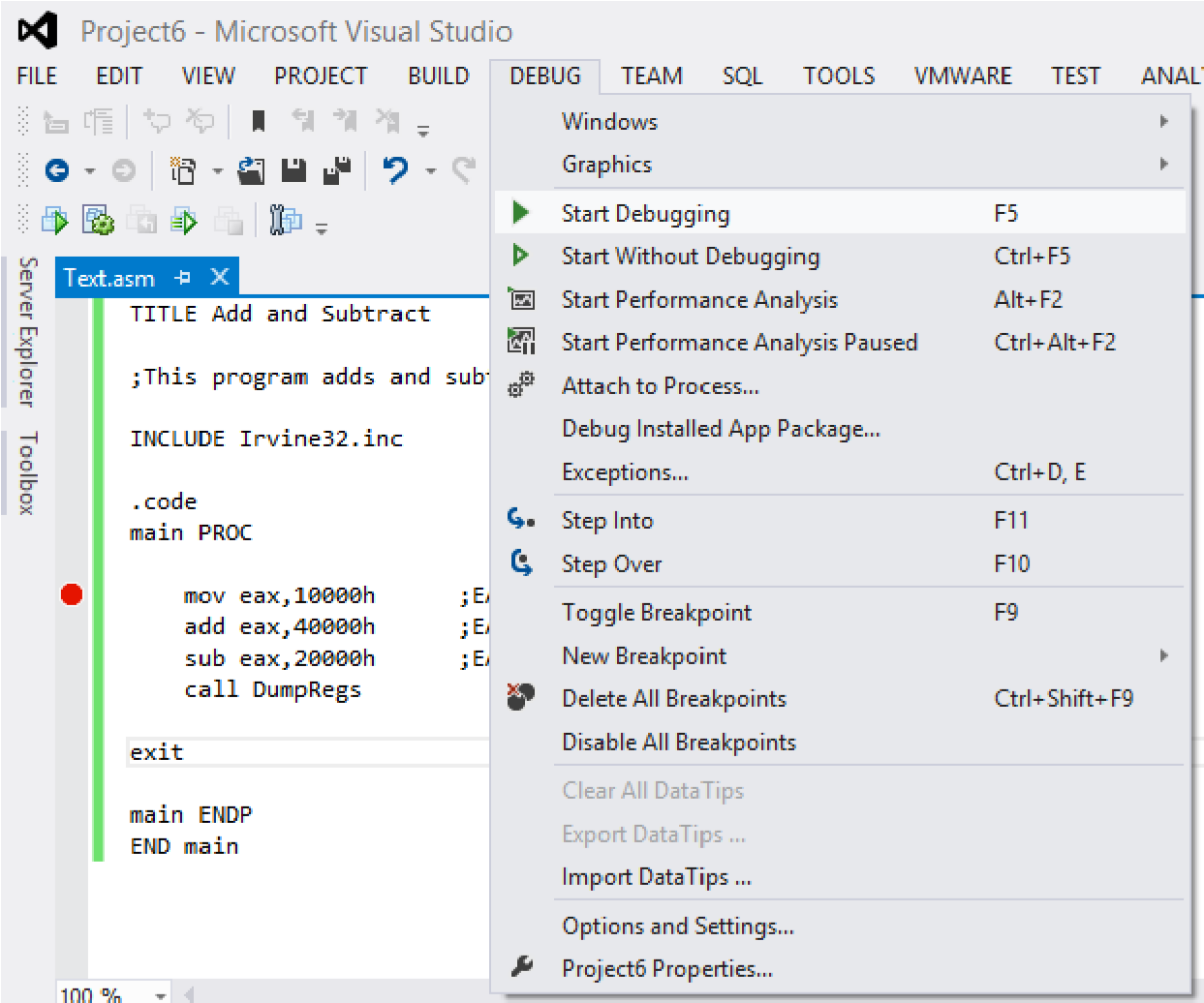
main ENDP END main

1. Right-click on line 6 to insert a breakpoint.



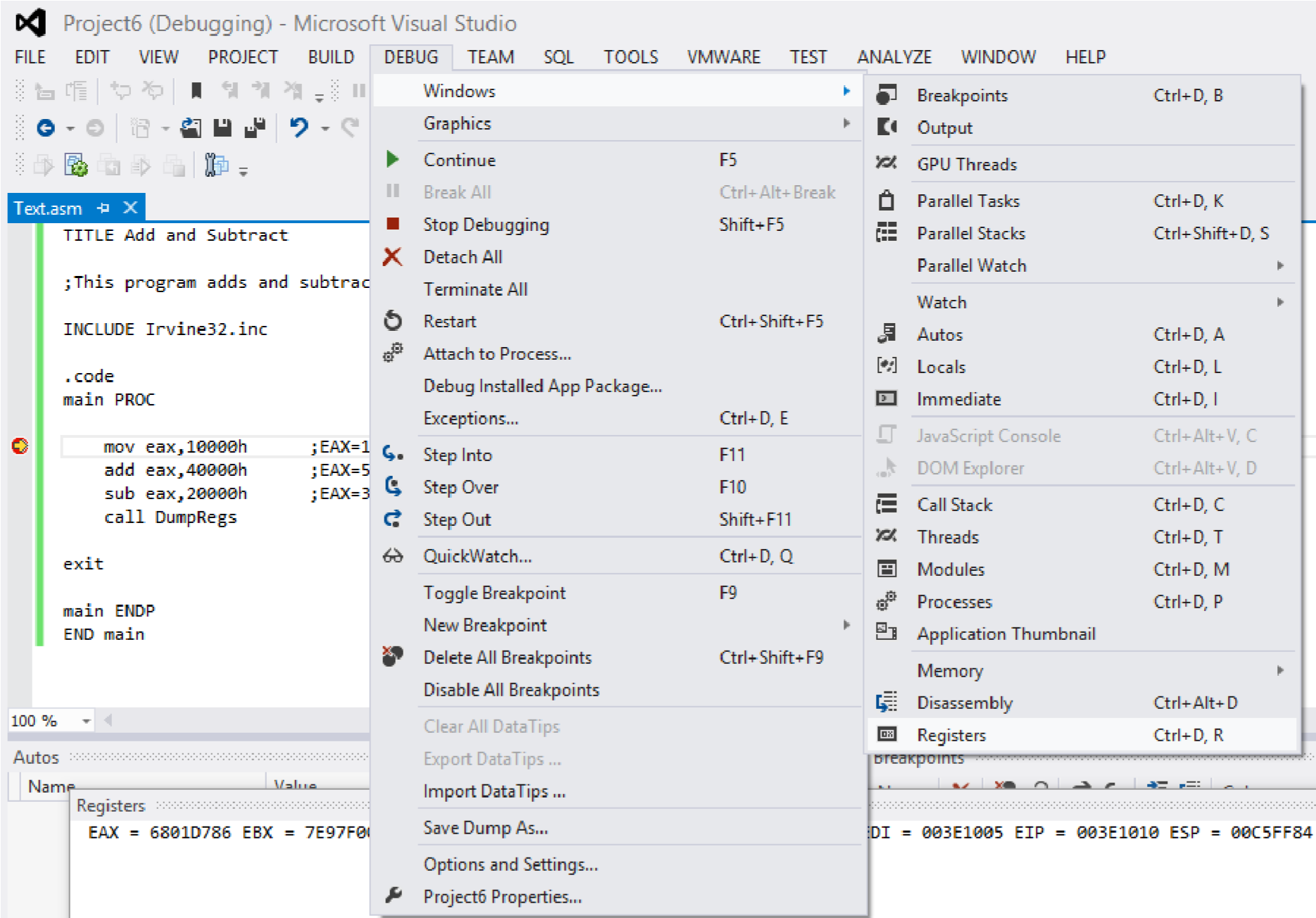


1. Click on **Debug** tab from the toolbar, select **Start Debugging** OR press **F10** to start stepping over the code.

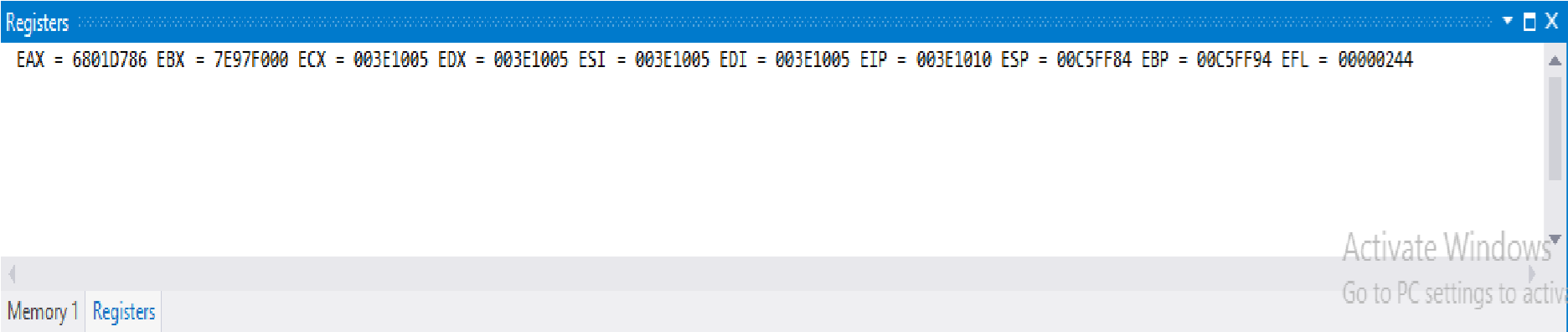
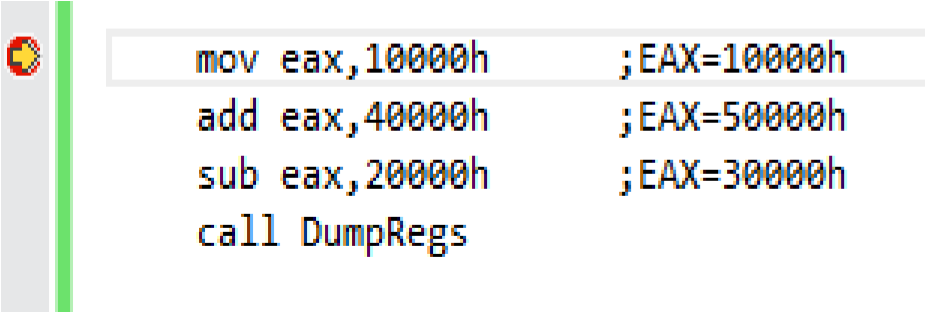


1. Click on **Debug** tab than select Windows after that open menu and select **Registers** option.

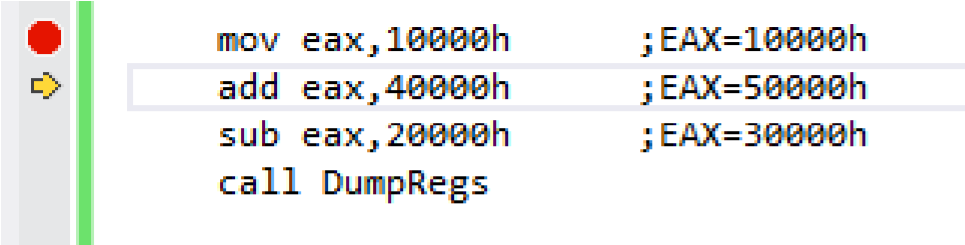


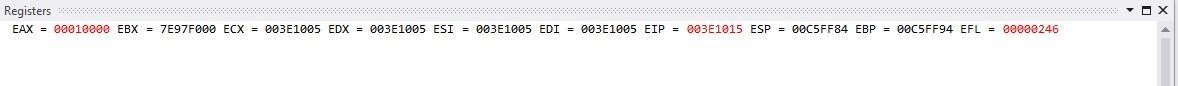


1. Breakpoint set on 1st instruction



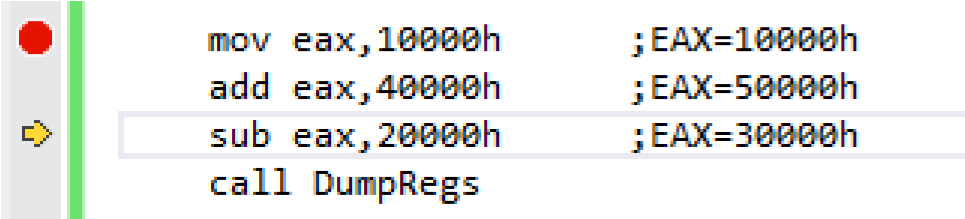
Press **F10** again to execute next line.

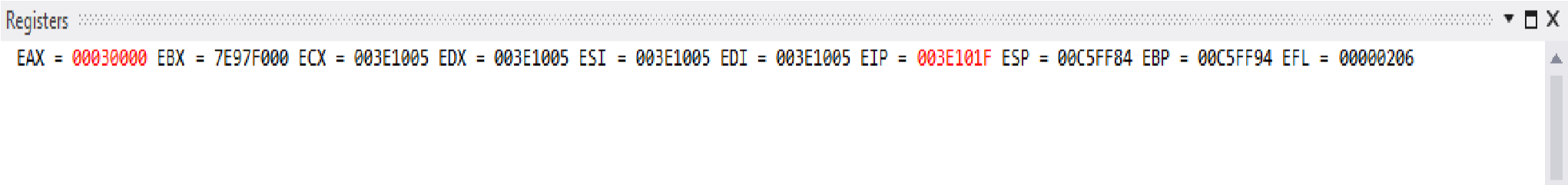
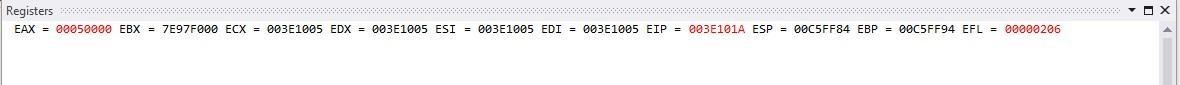




Again press **F10** key for next instruction execution.







Press **F10** again, the program will not terminate after executing the current instruction and as soon as it reaches the line with a call to **DumpRegs**

# SECTION 3: INTRODUCTION TO REGISTERS

To speed up the processor operations, the processor includes some internal memory storage locations, called **Registers**. The registers store data elements for processing without having to access the memory.

## PROCESSOR REGISTERS

There are ten 32-bit and six 16-bit processor registers in IA-32 architecture. The registers are grouped into three categories:

* General registers.
* Control registers.
* Segment registers.

Furthermore, the general registers are further divided into the following groups:

* Data registers.
* Pointer registers. ● Index registers.

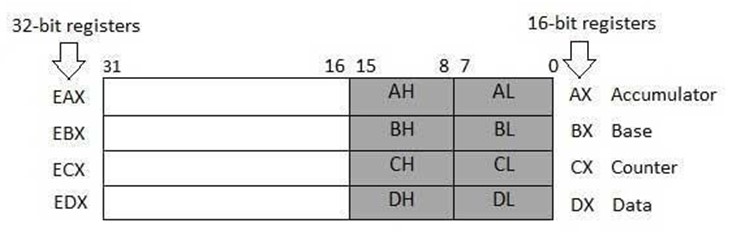


## DATA REGISTERS

Four 32-bit data registers are used for arithmetic, logical, and other operations. These 32-bit registers can be used in three ways:

* As complete 32-bit data registers: EAX, EBX, ECX, EDX.
* Lower halves of the 32-bit registers can be used as four 16-bit data registers: AX, BX, CX and DX.
* Lower and higher halves of the above-mentioned four 16-bit registers can be used as

eight 8-bit data registers: AH, AL, BH, BL, CH, CL, DH, and DL



**AX (Accumulator**): It is used in input/output and most arithmetic instructions. For example, in multiplication operation, one operand is stored in EAX or AX or AL register according to the size of the operand.

**BX (Base register**): It could be used in indexed addressing.

**CX (Counter register)**: The ECX, CX registers store the loop count in iterative operations.

**DX (Data register):** It is also used in input/output operations. It is also used with AX register along with DX for multiply and division operations involving large values.



## POINTER REGISTERS

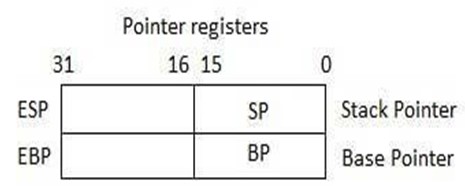
The pointer registers are 32-bit EIP, ESP, and EBP registers and corresponding 16-bit right portions IP, SP, and BP. There are three categories of pointer registers:

**Instruction Pointer (IP)**: The 16-bit IP register stores the offset address of the next instruction to be executed. IP in association with the CS register (as CS:IP) gives the complete address of the current instruction in the code segment.

**Stack Pointer (SP):** The 16-bit SP register provides the offset value within the program stack. SP in association with the SS register (SS:SP) refers to be current position of data or address within the program stack.

**Base Pointer (BP):** The 16-bit BP register mainly helps in referencing the parameter variables passed to a subroutine. The address in SS register is combined with the offset in BP to get the location of the parameter. BP can also be combined with DI and SI as base register for special addressing.



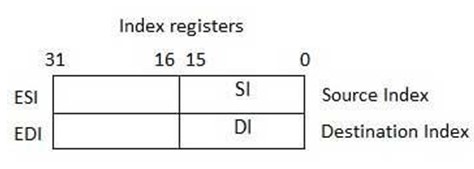


**Index Registers**

The 32-bit index registers, ESI and EDI, and their 16-bit rightmost portions. SI and DI, are used for indexed addressing and sometimes used in addition and subtraction. There are two sets of index pointers.

**Source Index (SI):** It is used as source index for string operations.

**Destination Index (DI):** It is used as destination index for string operations.



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**I**

**NTEGER**

**C**

**ONSTANTS**

Integer constants are made up of an optional leading sign, one or more digits and an optional suffix

character.

***Format:***

[

{+ | -}] digits radix

***Examples:***

26

for decimal

d for decimal

26

10111110

b for binary

42

o for octal

1

Ah for Hexadecimal

0

A3h for Hexadecimal

**C**

**HARACTER**

**C**

**ONSTANTS**

Character constants are made up of a single character enclosed in either single or double quotes.

***Example:***

'A' "d"

**S**

**TRING**

**C**

**ONSTANTS**

A string of characters enclosed in either single or double quotes.

***Example:***

"Hello World"

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## IDENTIFIERS

An identifier is a programmer-defined name of a variable, procedure or code label.

***Format:***

They may contain between 1 and 247 characters. They are not case sensitive. The first character must be a letter (A..Z, a..z), underscore (\_), @ , ?, or $. Subsequent characters may also be digits.

An identifier cannot be the same as an assembler reserved word. For example: reserved words are instruction mnemonics, directives, attributes, operators, predefined symbols.

***Examples:***

myVar \_abc hello2

## MEMORY SEGMENTS



A segmented memory model divides the system memory into groups of independent segments referenced by pointers located in the segment registers. Each segment defines the area of our program that contains data variables, code and stack, respectively.

**Data segment:** It is the memory region, where data elements are stored for the program. This section cannot be expanded after the data elements are declared, and it remains static throughout the program.

**Code segment:** This section defines an area in memory that stores the instruction codes. This is also a fixed area.

**Stack segment:** This segment contains data values passed to procedures within the program.

## DIRECTIVES

A directive is a command embedded in the source code that is recognized and acted upon by the assembler. Directives do not execute at runtime. They can assign names to memory segments. In

MASM,

directives

are

case

insensitive.

For

example,

it

recognizes

.data,

.DATA

and

.Data

as

equivalent.

Let us see what different directives we can use to define segments of our program:

The

**.DATA**

directive identifies the area of a program

containing variables:

***Syntax:***

.data

The

**.CODE**

directive identifies the area of a program

containing executable instructions:

***Syntax:***

.code

The

**.STACK**

directive identifies the area of a program

holding the runtime stack, setting its size:

***Syntax:***

.stack 100h

**I**

**NSTRUCTIONS**

An

*instruction*

is a statement that becomes executable

when a program is assembled. Instructions are

translated by the assembler into machine language bytes, which are loaded and executed by the

CPU at runtime. An instruction contains four basic parts:

●

Label (optional)

●

Instruction mnemonic (required)

●

Operand(s) (usually required)

●

Comment (optional)

The basic syntax of an Assembly Language instruction is as:

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**[*label*:] *mnemonic* [*operands*] [;*comment*]**

where elements in square brackets are optional. We will now see what each of these elements.

***Label:*** A *label* is an identifier that acts as a place marker for instructions and data. A label placed just before an instruction implies the instruction’s address. Similarly, a label placed just before a variable implies the variable’s address.

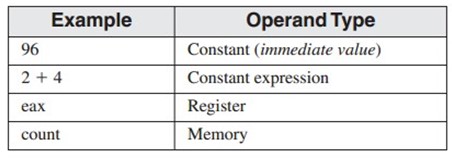
***Mnemonics:*** An instruction mnemonic is a short word that identifies an instruction to perform an operation. Following are examples of instruction mnemonics:

**mov**: Moves (assigns) one value to another.

**add**: Adds two values **sub**: Subtracts one value from another **mul**: Multiplies two values **jmp**: Jumps to a new location **call**: Calls a procedure



***Operands:*** Assembly language instructions can have between zero and three operands, each of which can be a register, memory operand, constant expression, or input-output port.



***Example:***

The MOV instruction has two operands:

**mov count , ebx ; move EBX to count**

In a two-operand instruction, the first operand is called the destination. The second operand is the

source. In general, the contents of the destination operand are modified by the instruction.

***Comments:***

Comments are an important way for

the writer of a program to communicate

information about the program’s design to a person reading the source code.

**Comments can be specified in two ways:**

•

**Single-line comments**

:

beginning with a semicolon

character (;). All characters following the

semicolon on the same line are ignored by the assembler.

•

**Block comments**

:

beginning with the COMMENT directive

and a user-specified symbol. For

example,

COMMENT !

This line is a comment.

This line is also a comment.

!

**D**

**ATA**

**T**

**YPES**

MASM defines

**intrinsic data types**

, each of which describes

a set of values that can be assigned to

variables and expressions of the given type.

**BYTE**

8-

bit unsigned integer

**SBYTE**

8-

bit signed integer. S stands for

signed

**WORD**

bit unsigned integer

16-

**SWORD**

16-

bit signed integer

**DWORD**

32-

bit unsigned. D stands for double

**QWORD**

64-

bit integer. Q stands for quad

**TBYTE**

80-

bit integer. T stands for ten

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# SECTION 4: EXERCISE

Implement all of these equations in assembly language.

* 47 + 39 + 60 + 85 + 64+54o-0Ah
* 30- 9 + 186 – 150
* 101110 + 50Ah + 6710d + 1010001 + F



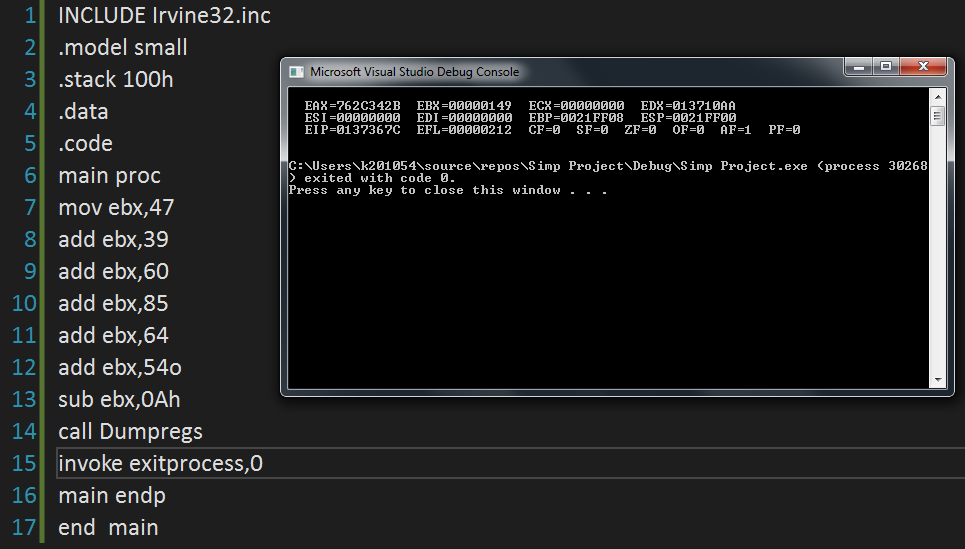
* 10001101 – D83h + 385+10 + 1111101 – E+F

Write a program in assembly language that implements following expression:

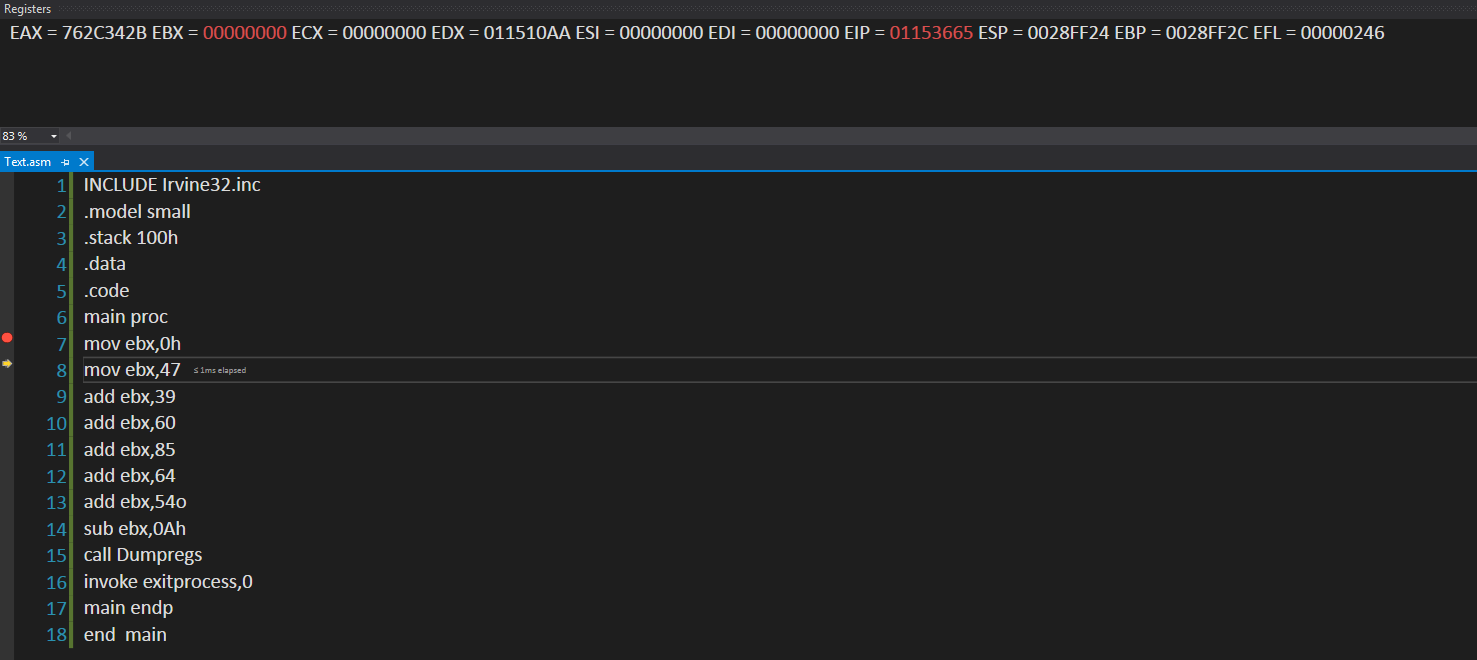
* edx = eax + 1 + ebx + edx – ecx + 0Ah-65o+73d
* eax = 5ADh – eax + 65o + 65d – 11110111 + 150

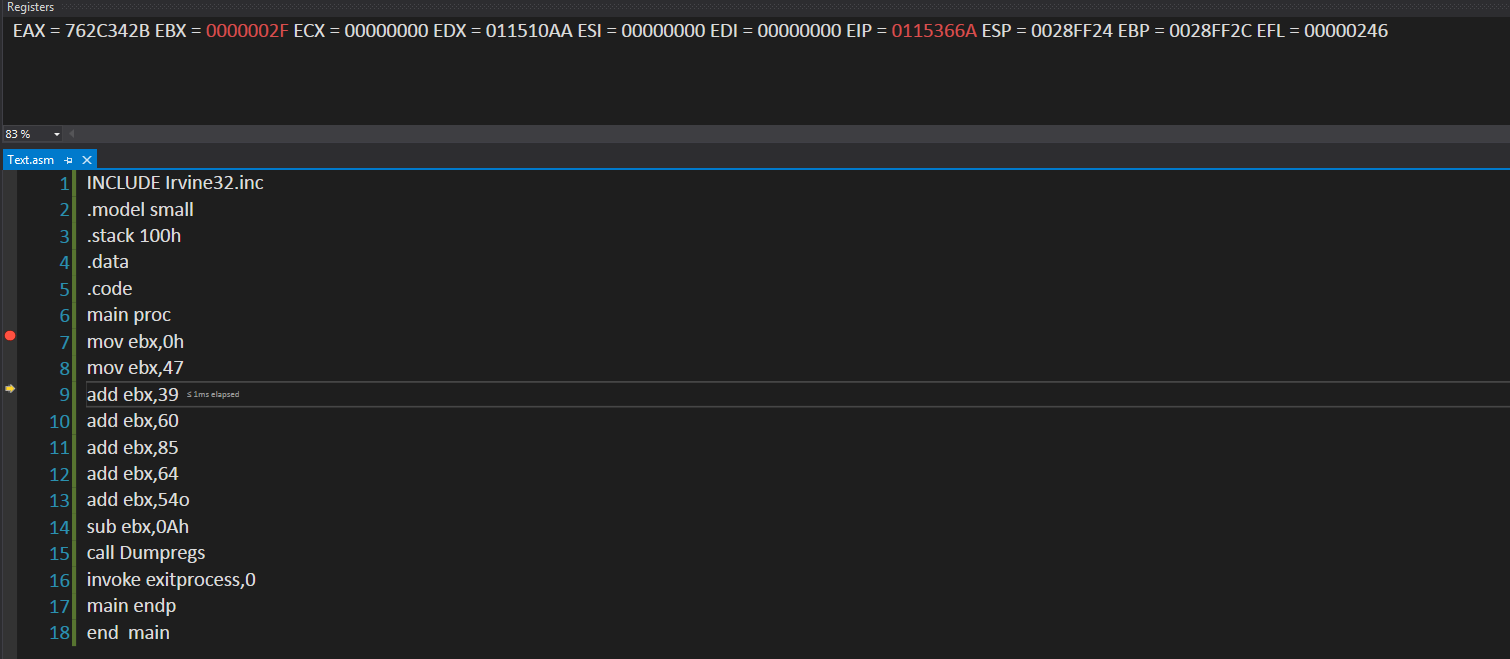
**COAL Lab 2 Tasks**

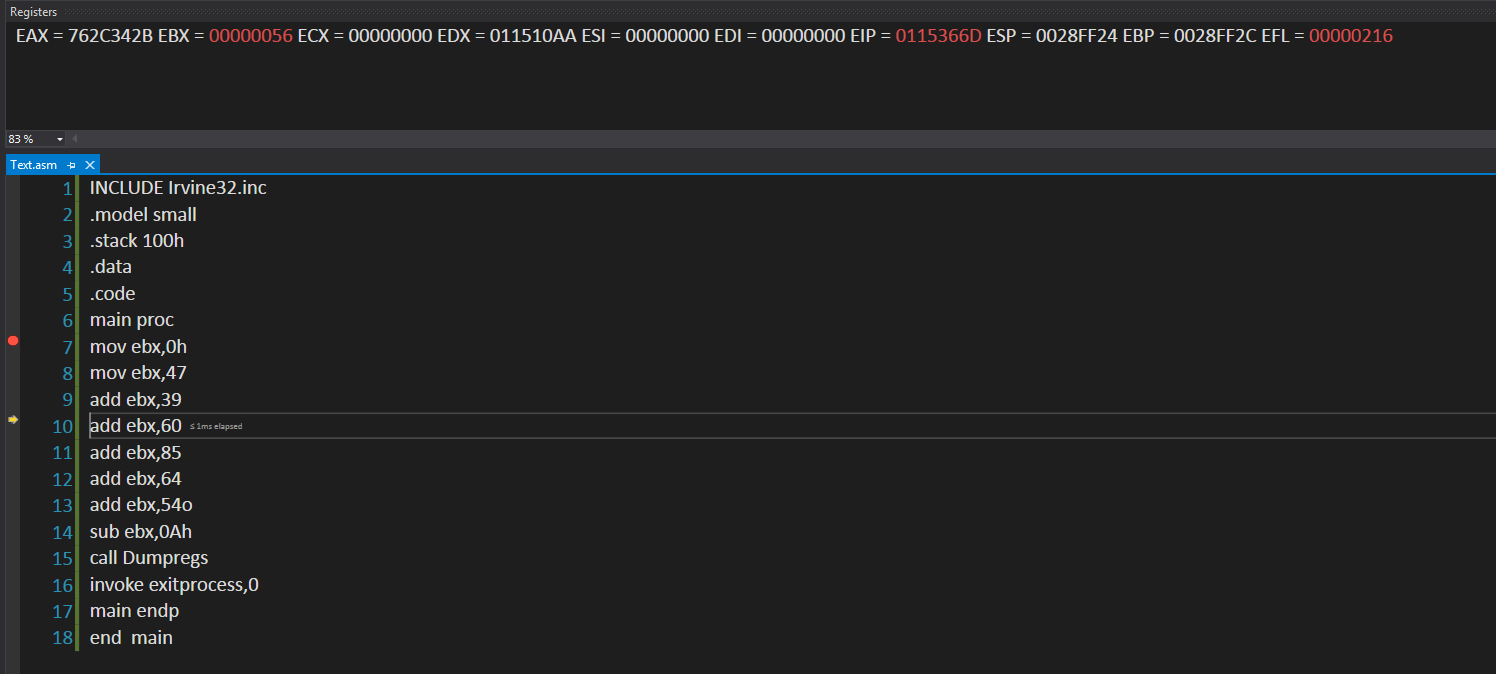
**Task # 1:**

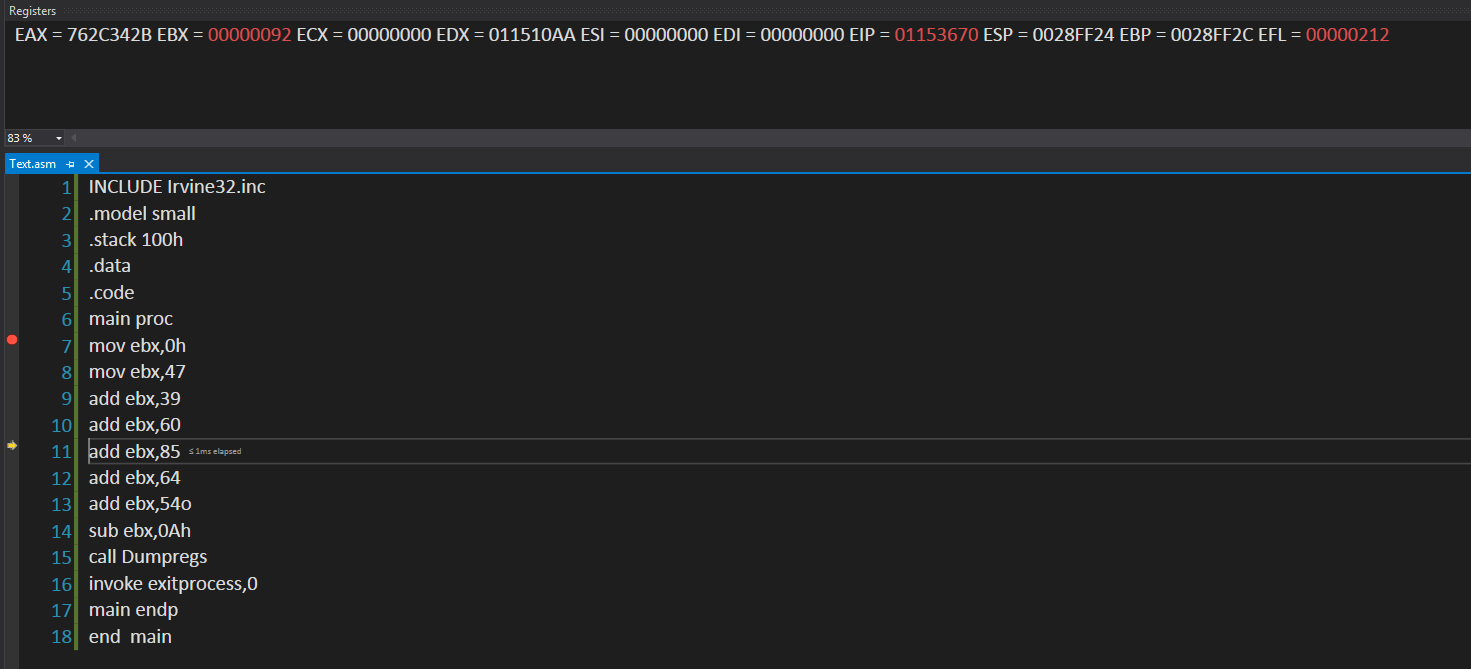
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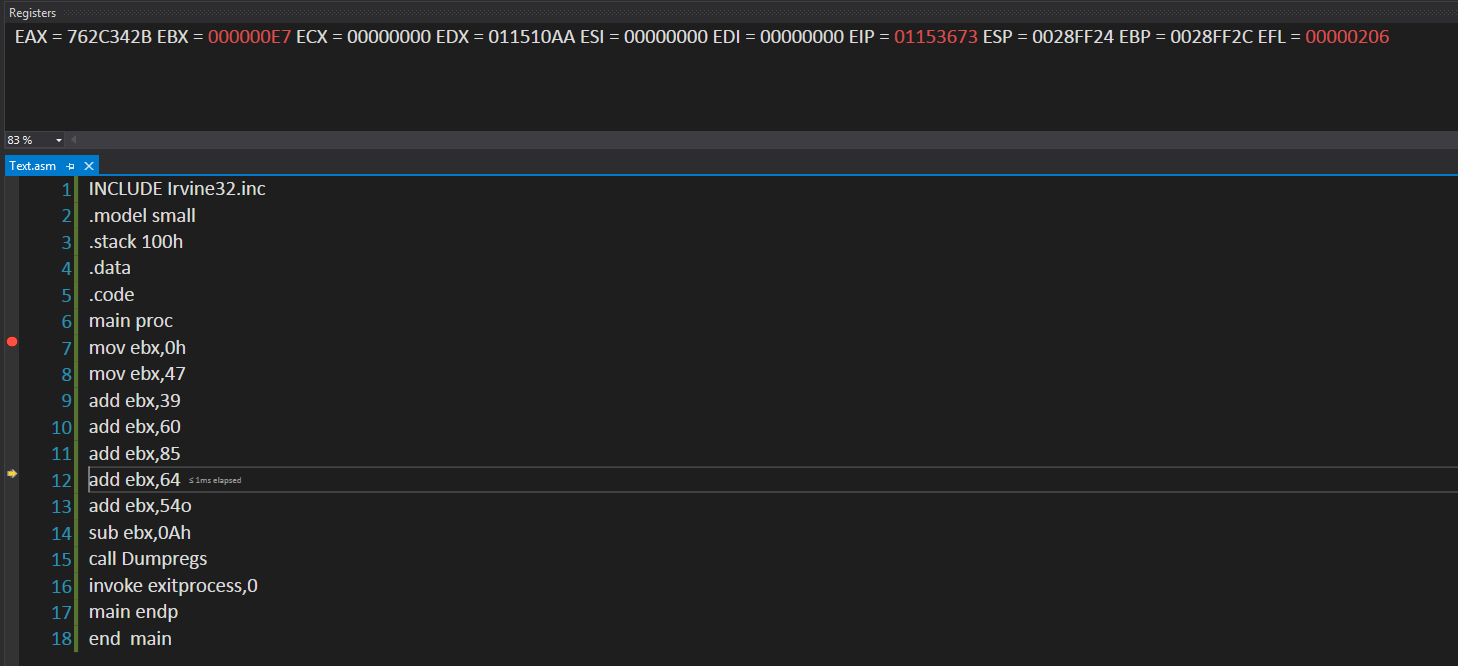
**Debugging:**

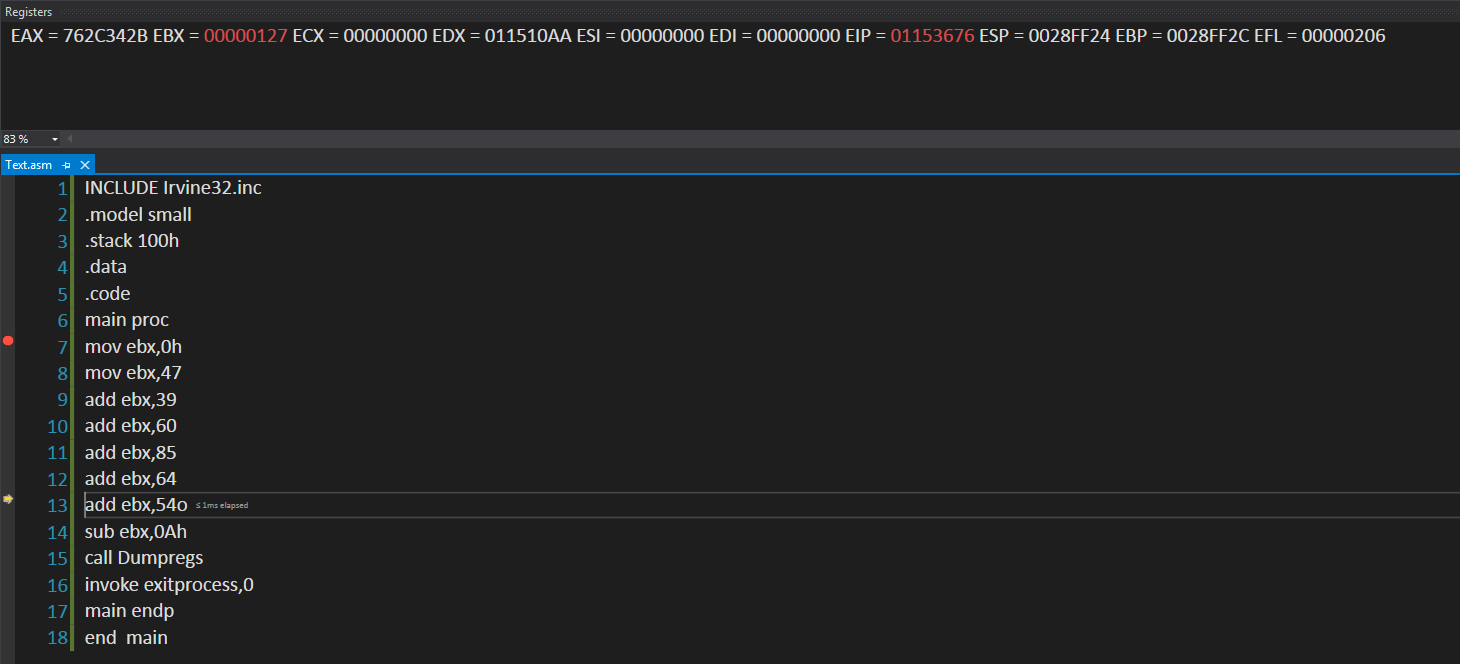
**Instruction # 1:**

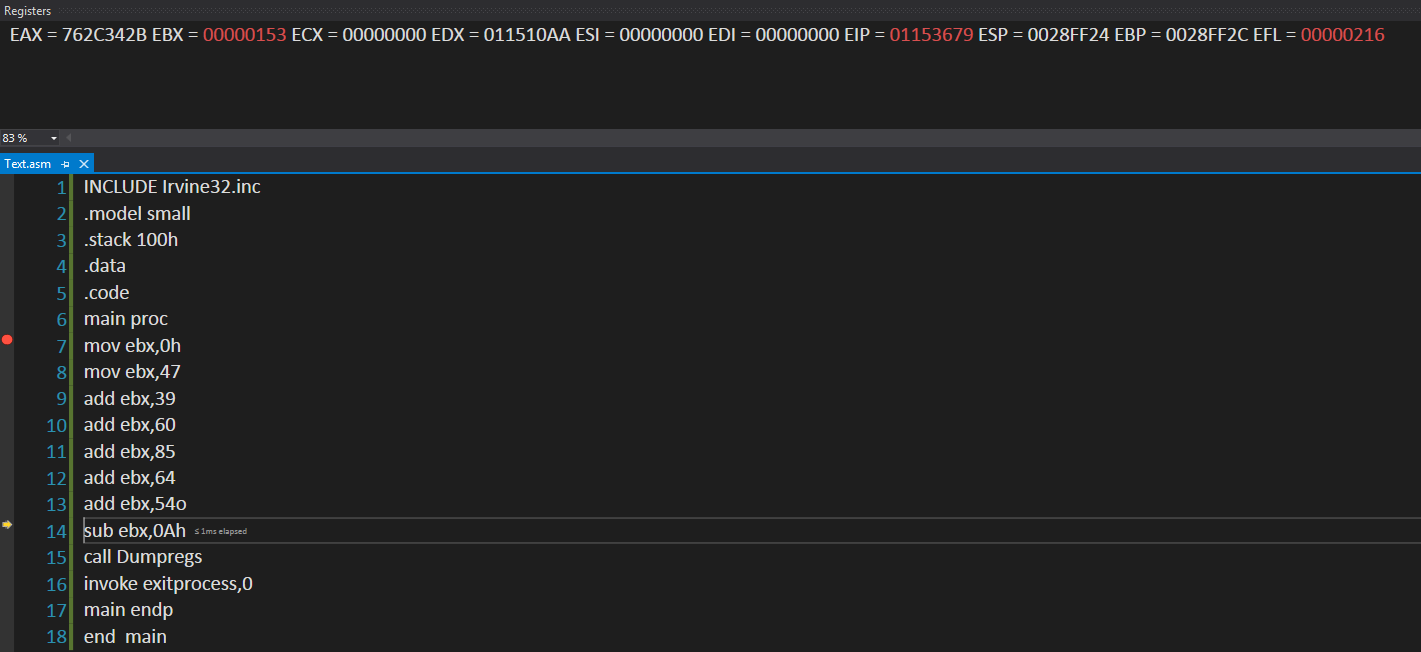
**Instruction # 2: **

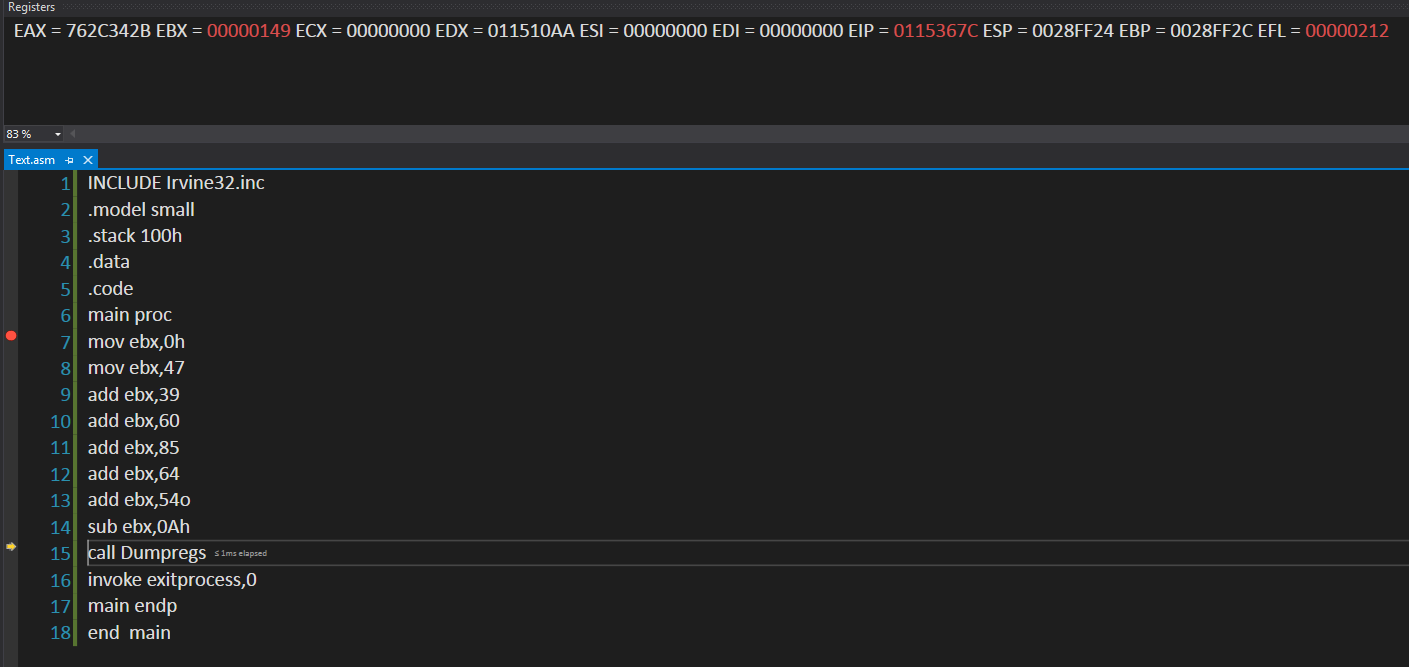
**Instruction # 3: **

**Instruction # 4: **

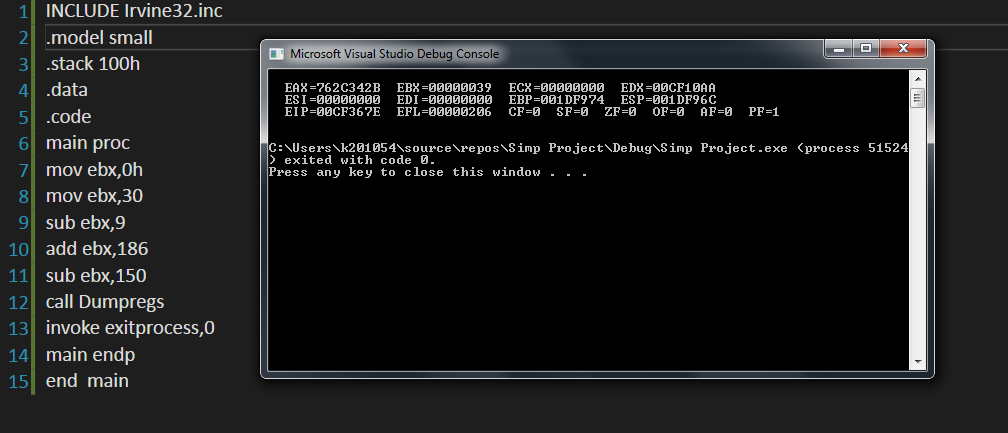
**Instruction # 5: **

**Instruction # 6: **

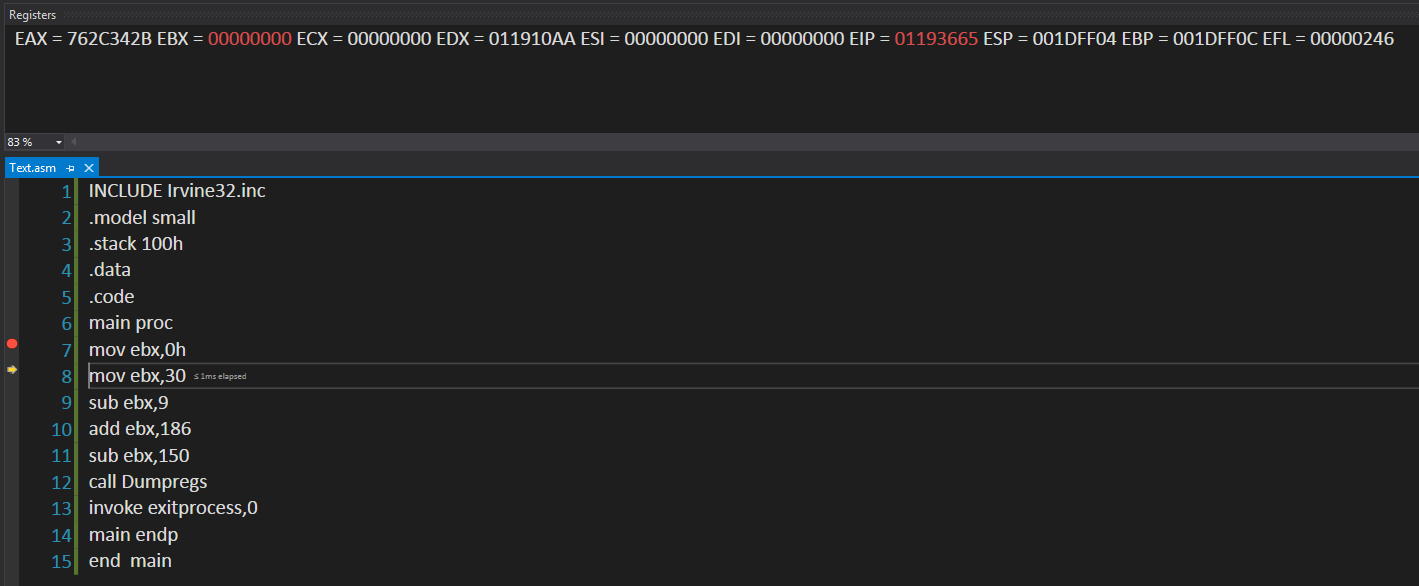
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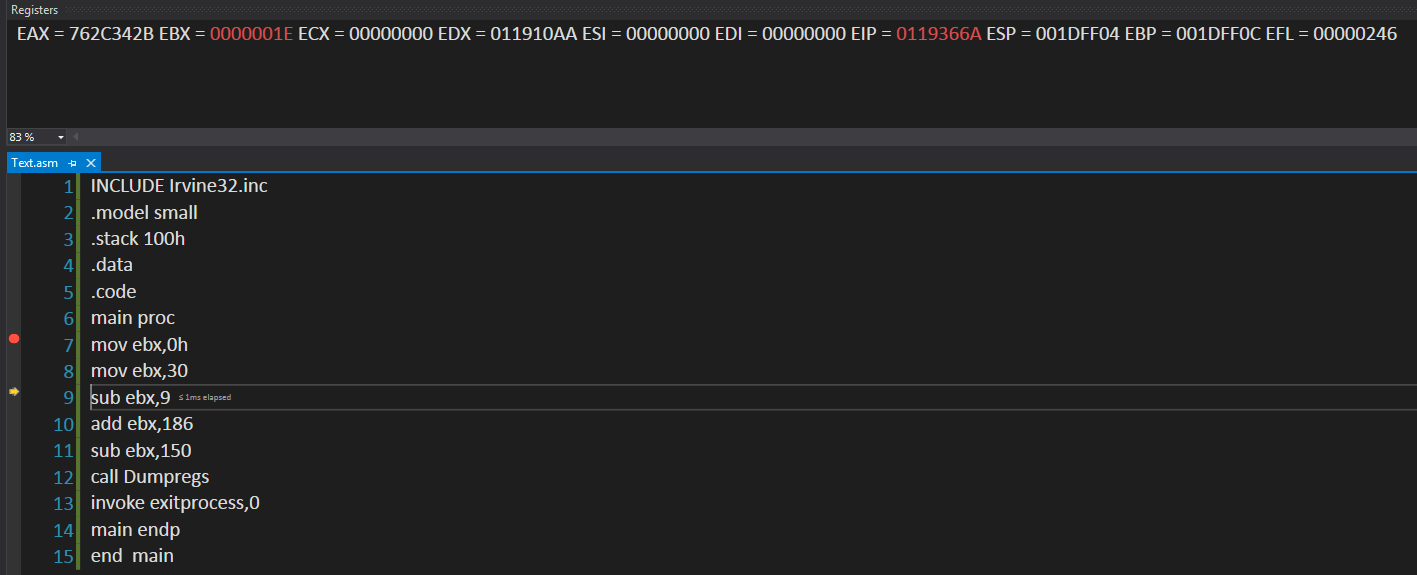
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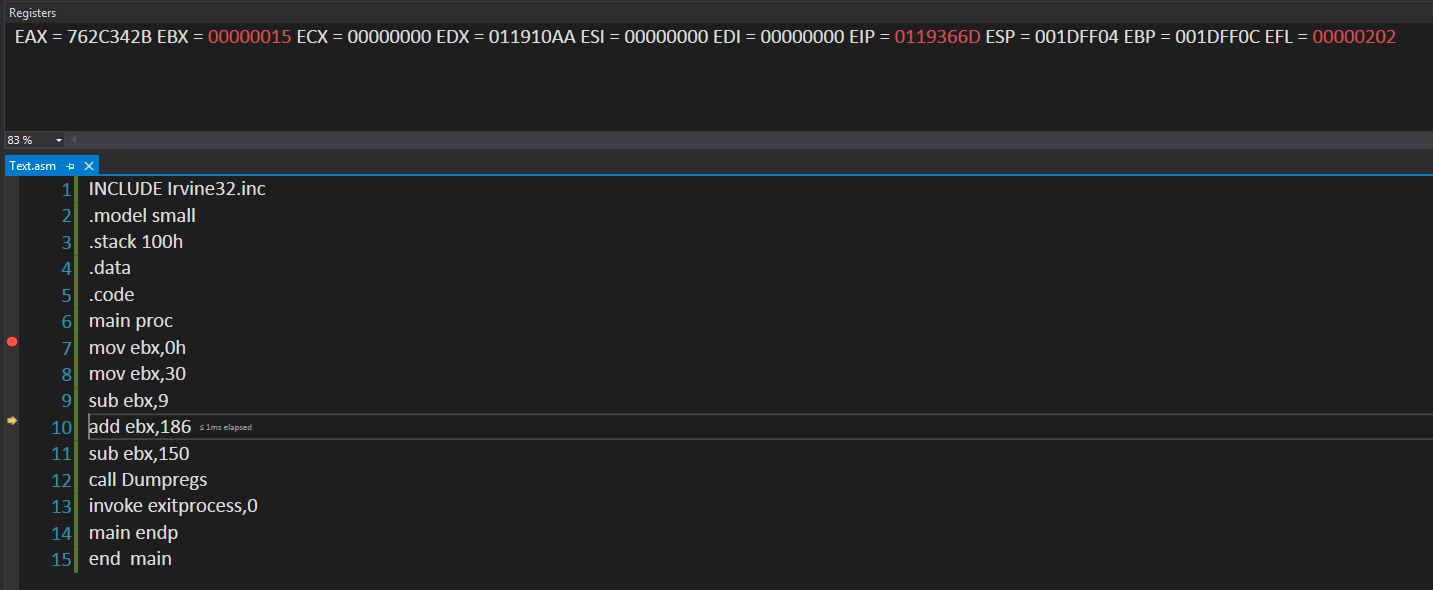
**Task # 2:**

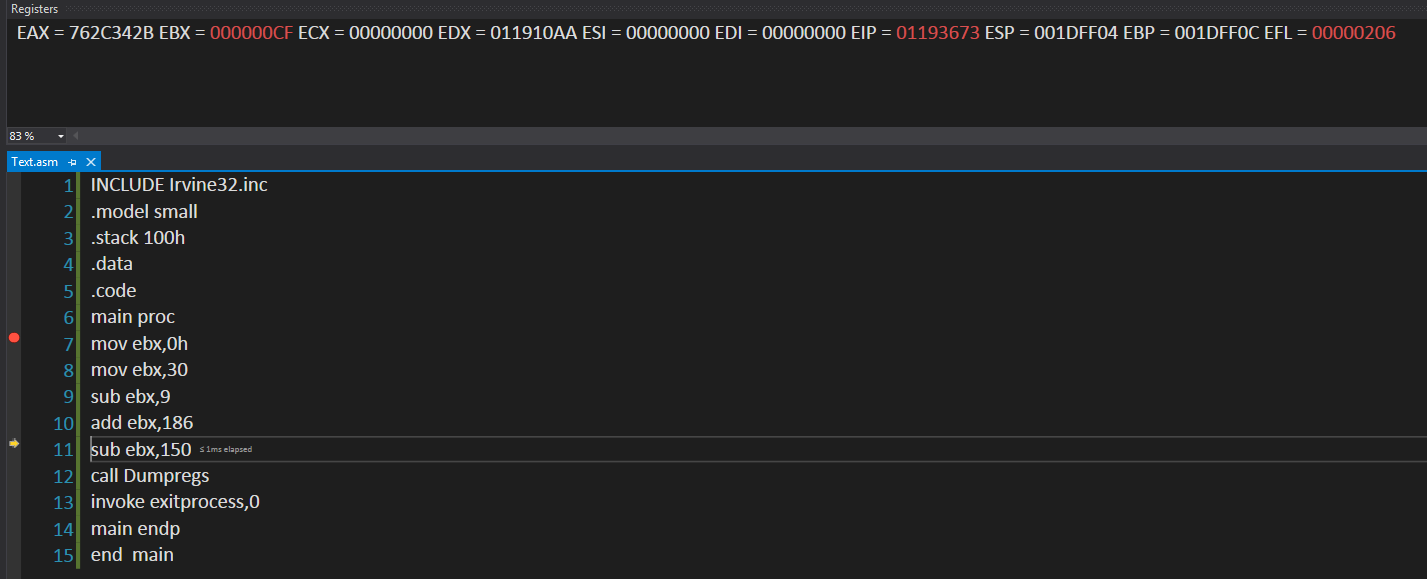
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**Debugging:**

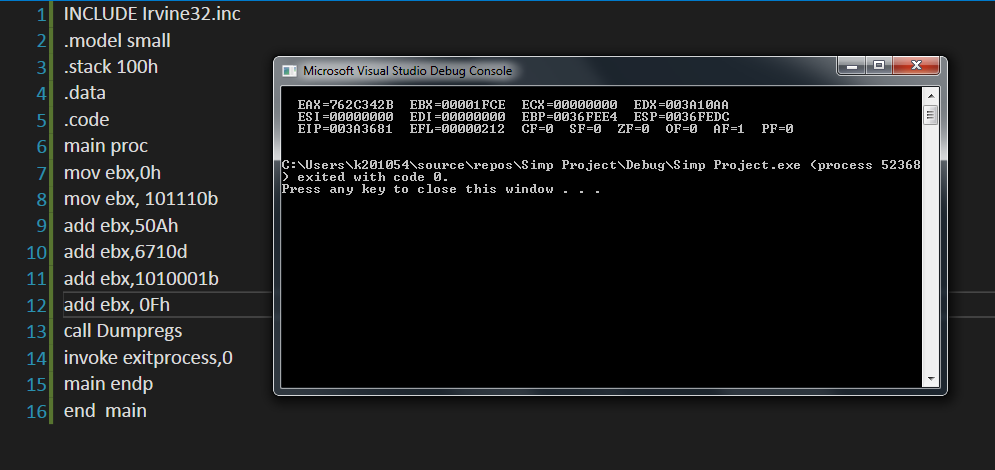
**Instruction # 1:**

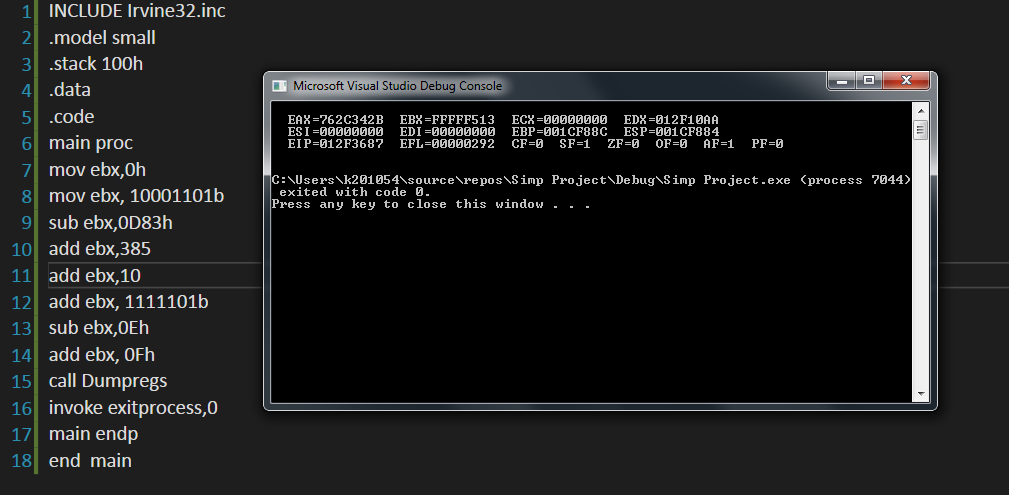
**Instruction # 2: **

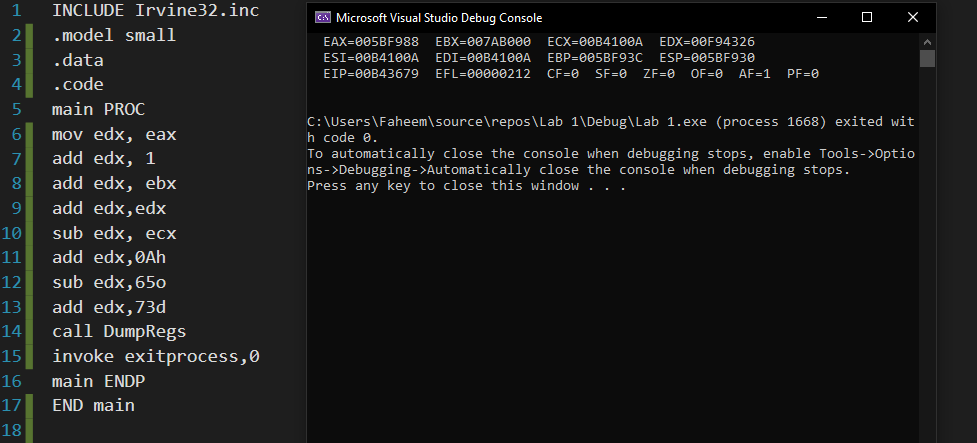
**Instruction # 3: **

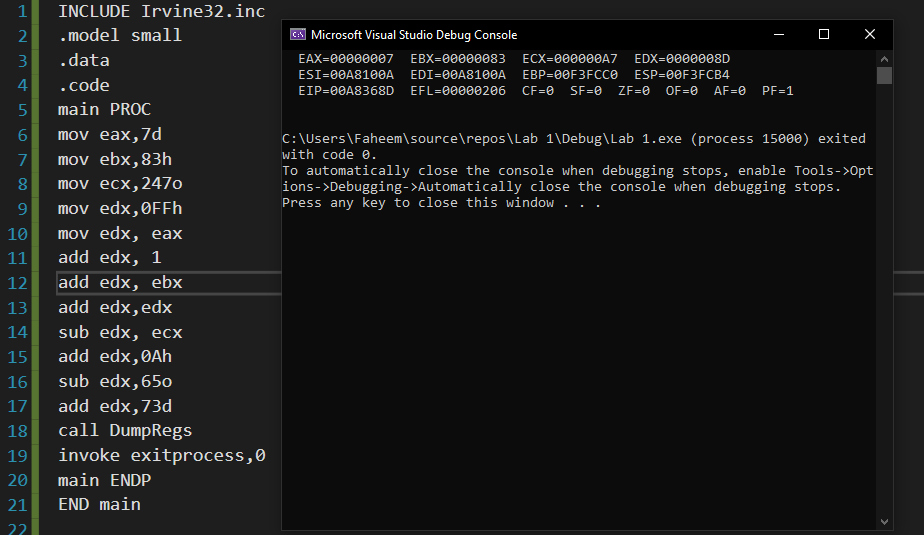
**Instruction # 4: **

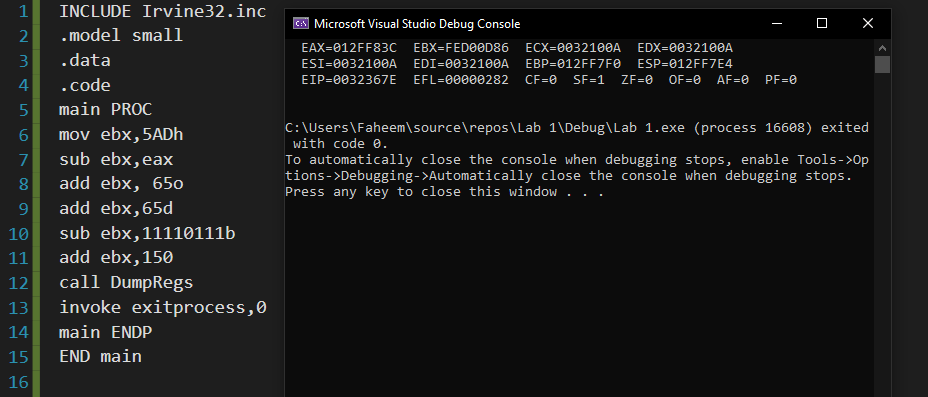
**Task # 3:**

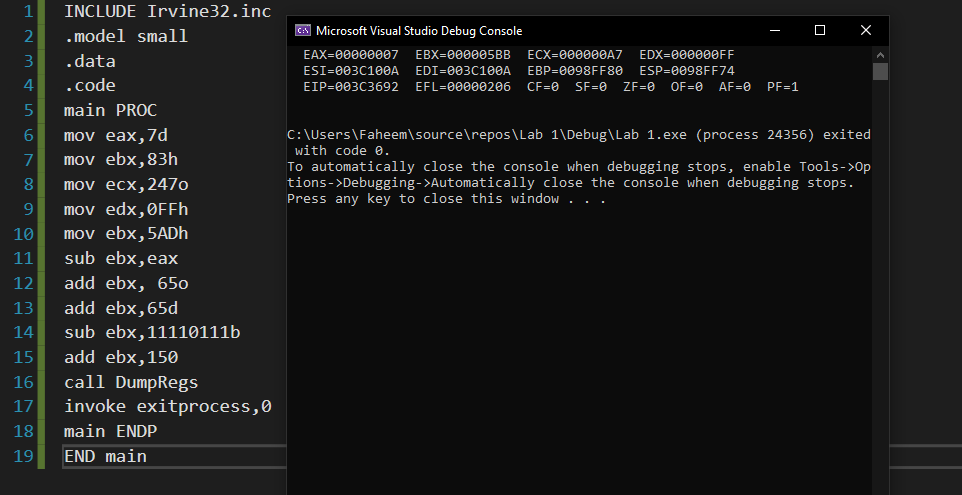
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**Task # 4: **

**Part 2 Task # 1 (Without Values):**

**Part 2 Task # 1 (With Values): **

**Part 2 Task # 2 (Without Values): **

**Part 2 Task # 2 (With Values): **